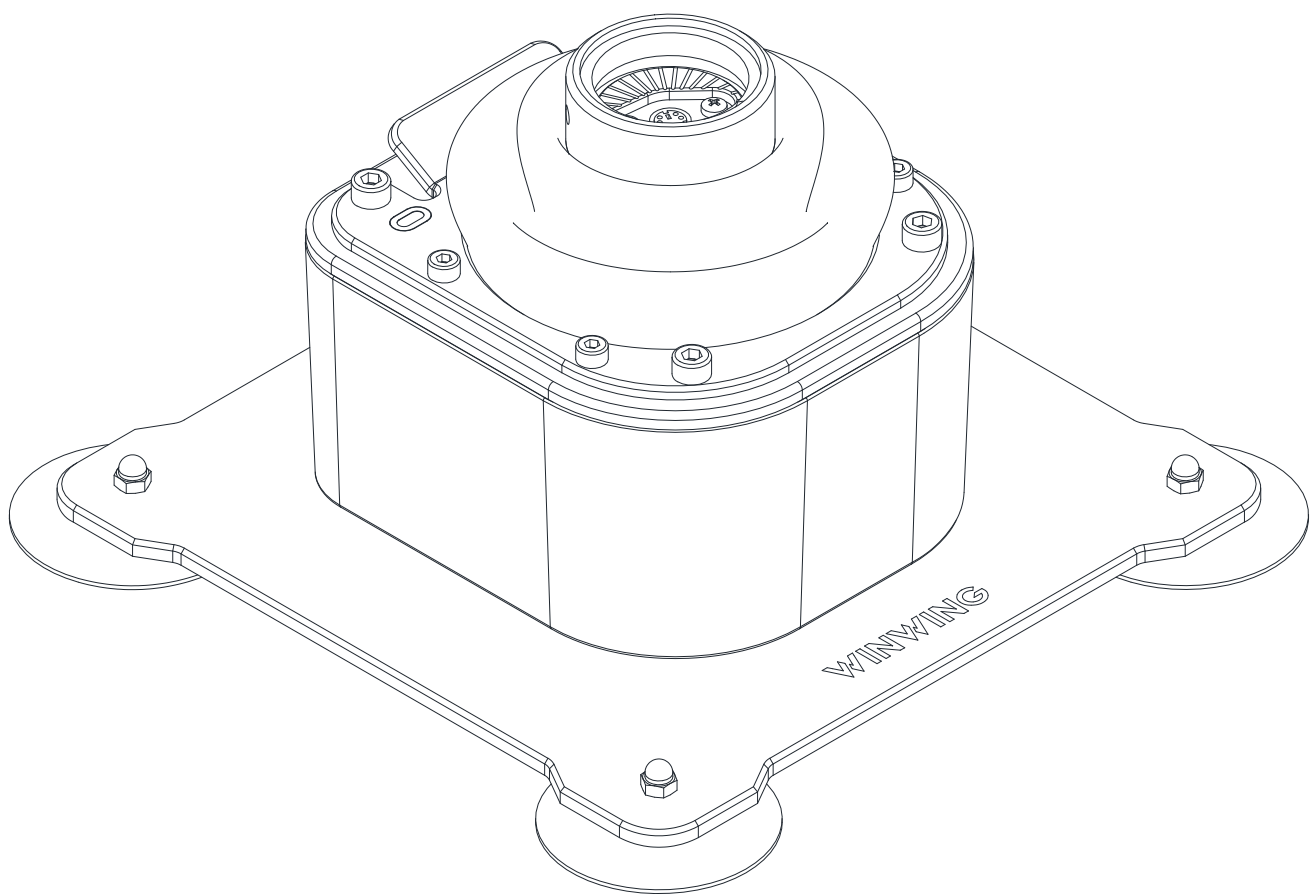


J2-2-BASE

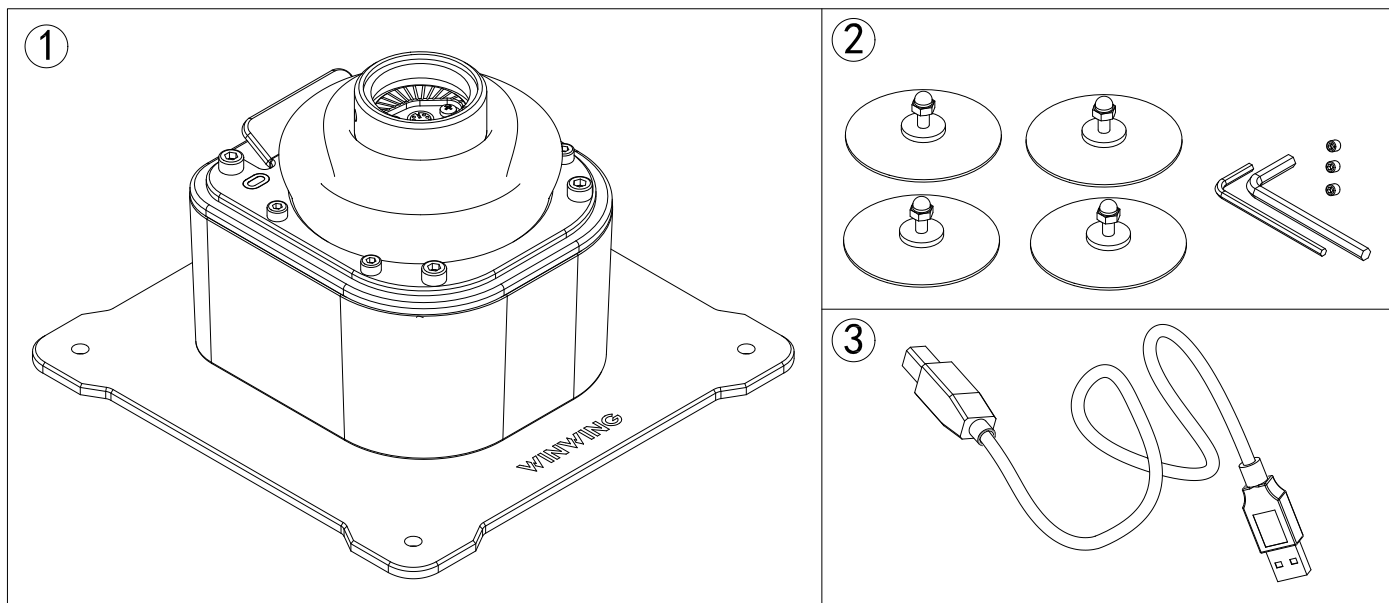
User Manual V1.2 2022.06



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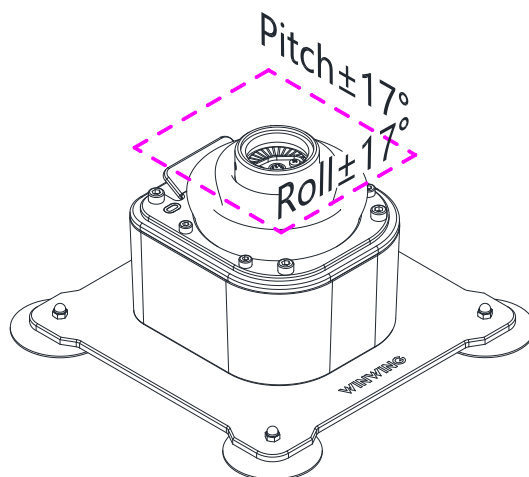


| | |
|------------------------|---|
| ① J2-2-BASE (1#) | 1 |
| ② Accessories Bag (2#) | 1 |
| ③ USB cable (3#) | 1 |

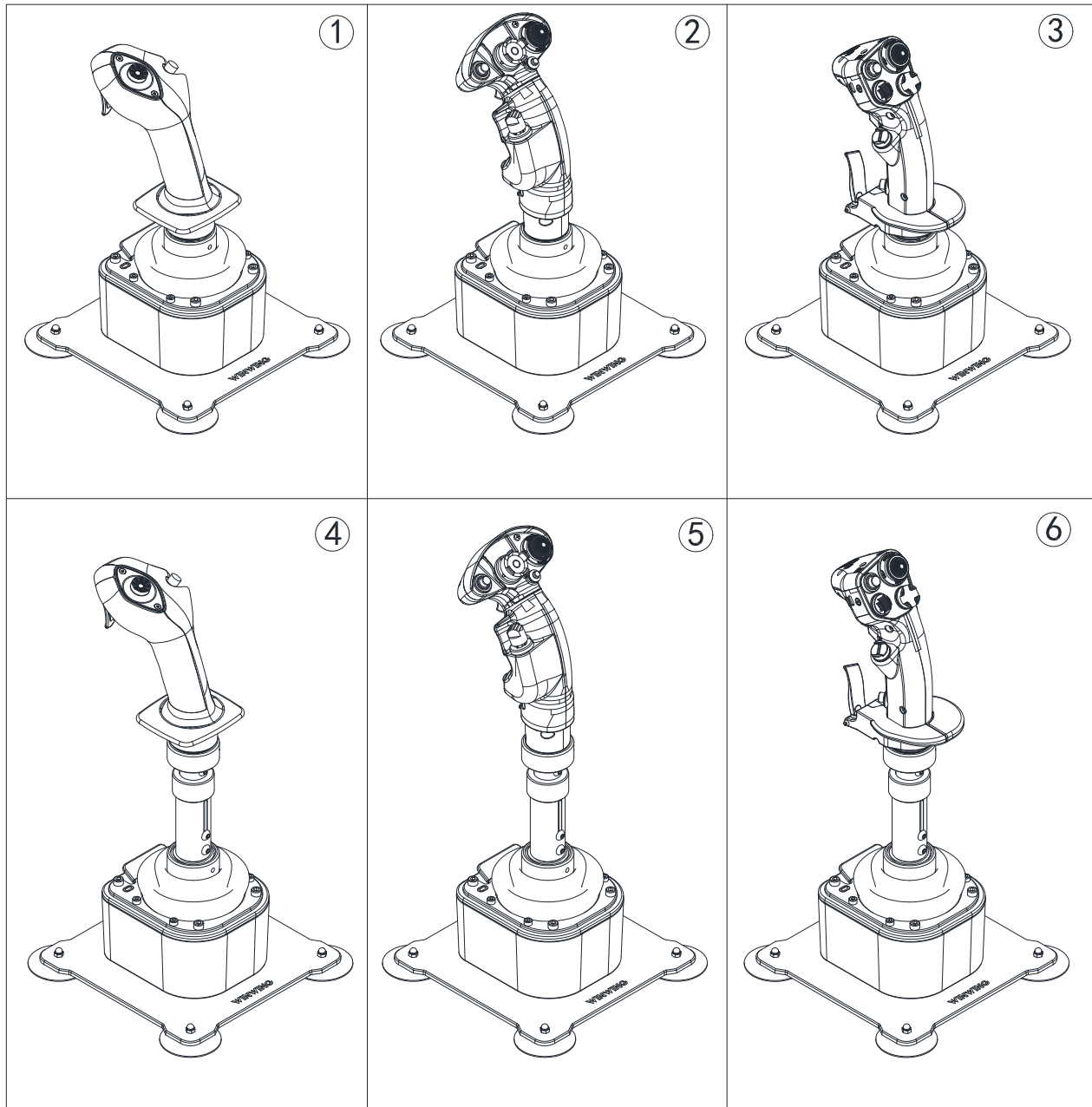
1 Key features

1.1 Performance

1. The deflection angle of pitch and roll: $\pm 17^\circ$;
2. Expandable with the force feedback module*
3. Resistance model* ;
4. Movable force sensor mode*.



1.2 Applicable Model



① J2-2-BASE+A320

② J2-2-BASE+JGRIP18

③ J2-2-BASE+JGRIP16

④ J2-2-BASE+ EXTENSION1+A320

⑤ J2-2-BASE+EXTENSION1+JGRIP18

⑥ J2-2-BASE+EXTENSION1+JGRIP16

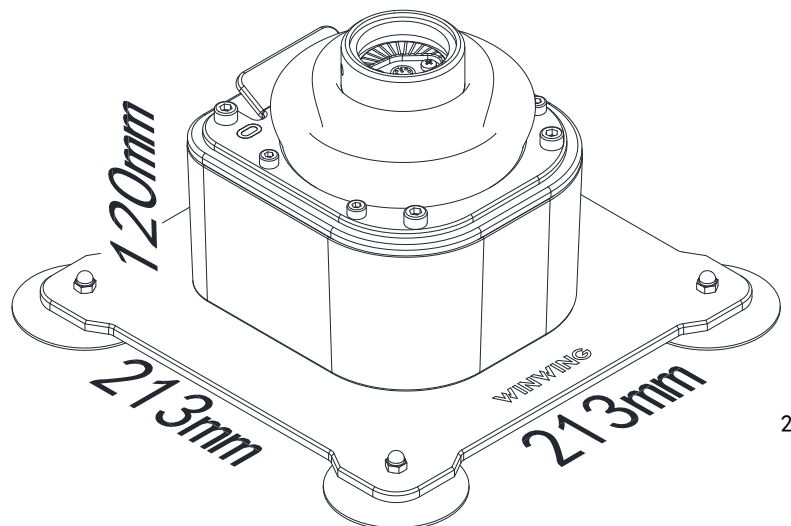
For installation please
reference :4. 1.

1.3 External Dimension

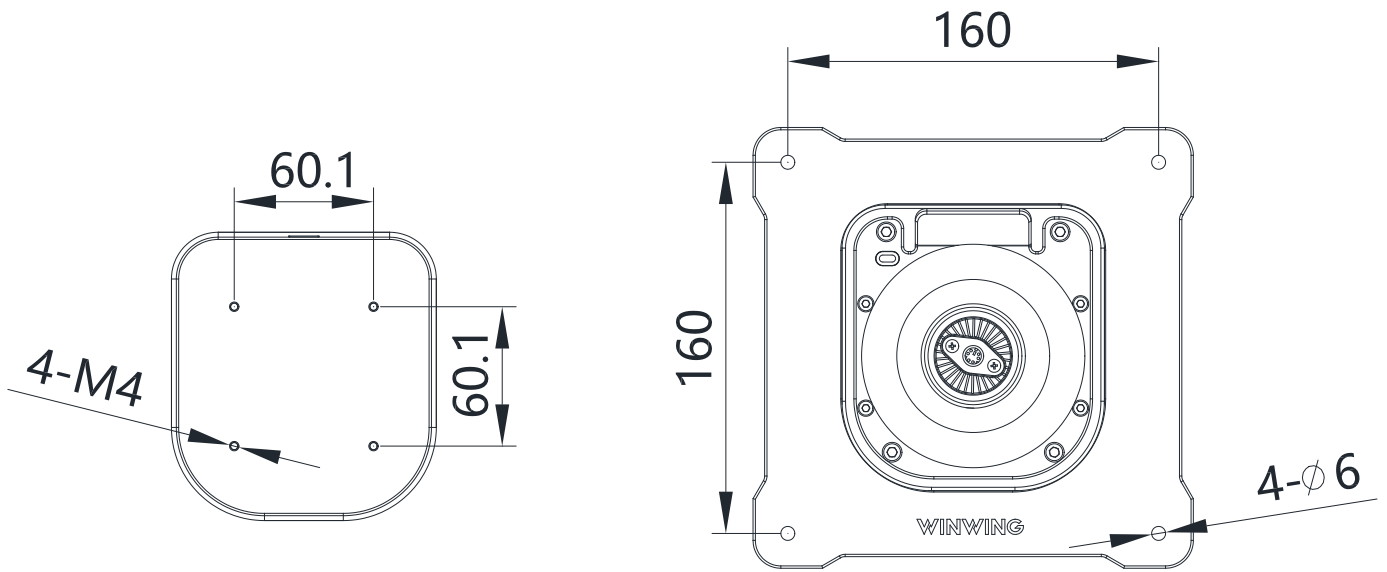
(Length/Width/Height) 213mm*213mm*120mm ;

0mm ;

Weight:1.5kg=25.35lb.



1.4 Installation dimension



Available installation holes:

4-Ø6 间距为 160*160。

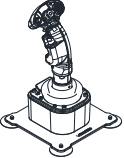



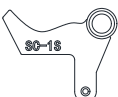







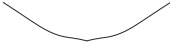

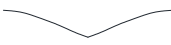




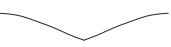
The space of 4-M4: 60.1mm*60.1mm ;

The space of -Ø6: 160* 160.

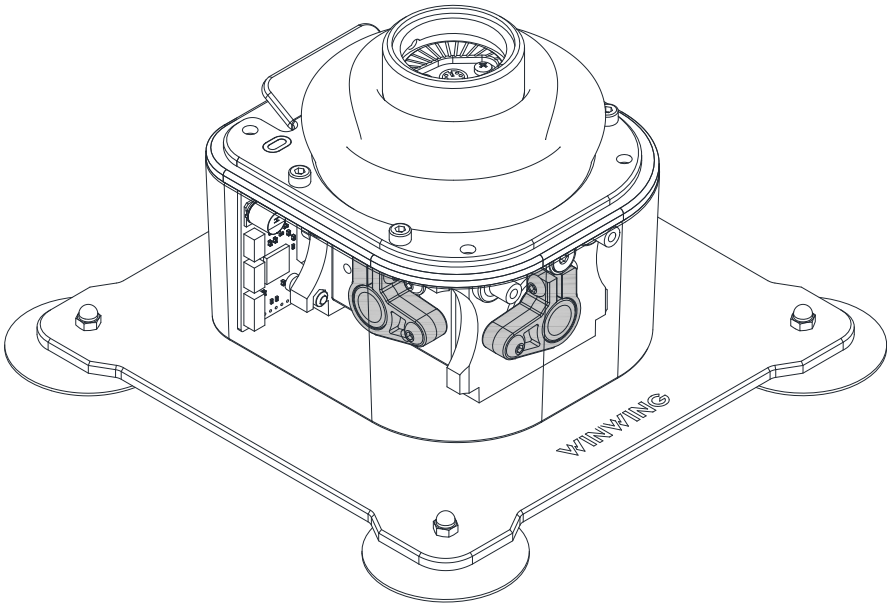
2 Functions

2.1 Mechanical and additional functions

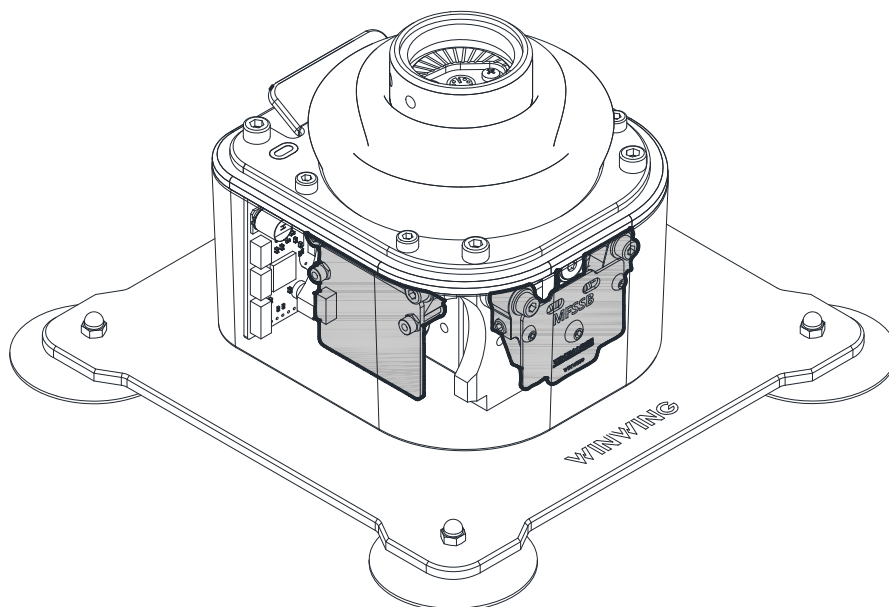
1. To expand force feedback module* you need to purchase EX1-J2-2 (For Installation please refer to: 3.2.) ;

| | | | | |
|--|--|--|---|--|
|  |  |  |  |  |
|  拉簧0.8 Spring0.8 | 1.3KG  | 1.3KG  | 1.3KG  | 1.3KG  |
|  拉簧1.0 Spring1.0 | 2.5KG  | 2.5KG  | 2.5KG  | 2.5KG  |
|  拉簧1.2 Spring1.2 | 4.5KG  | 4.5KG  | 4.5KG  | 4.5KG  |

2. For resistance model* you need to purchase EX 1-J2- 2 (For Installation please refer to: 3.3.) ;

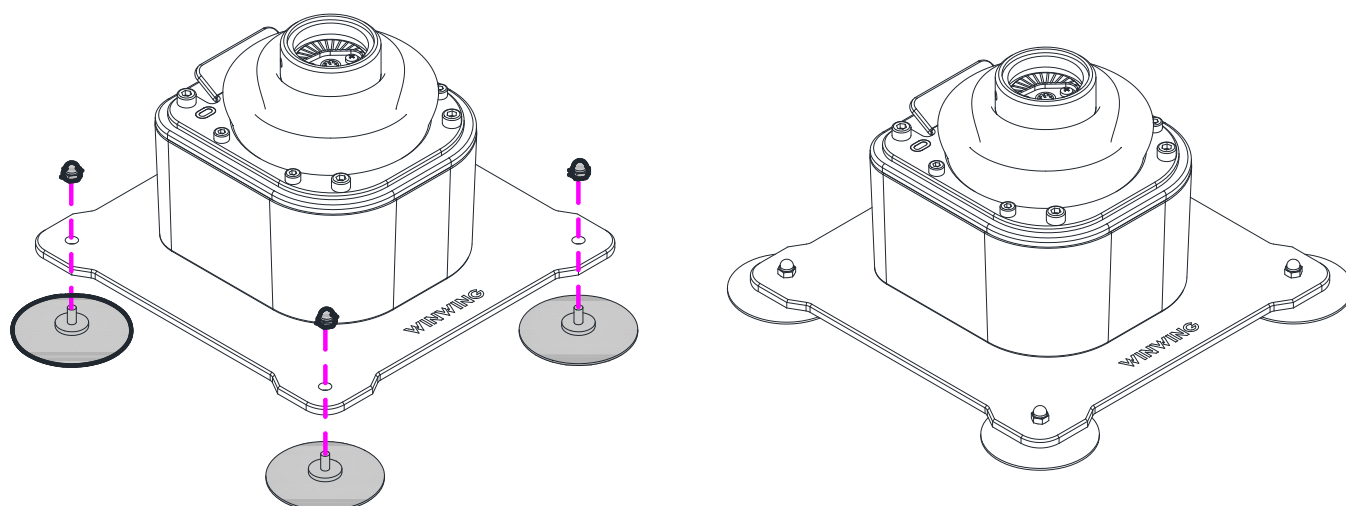


3. For sensor model* you need to purchase EX2-J2 -2 (For Installation please refer to: 3.4.) .



3 Parts installation

3.1 Suction cups installation



- ① Remove four nuts on the suction cups. Insert four screws through the plate, then tighten the nuts.

Note: Please clean the suction cups and your desk before installation.

3.2 Cams installation

Please refer to *EX1-J2-2 User Manual*.

3.3 Resistance model

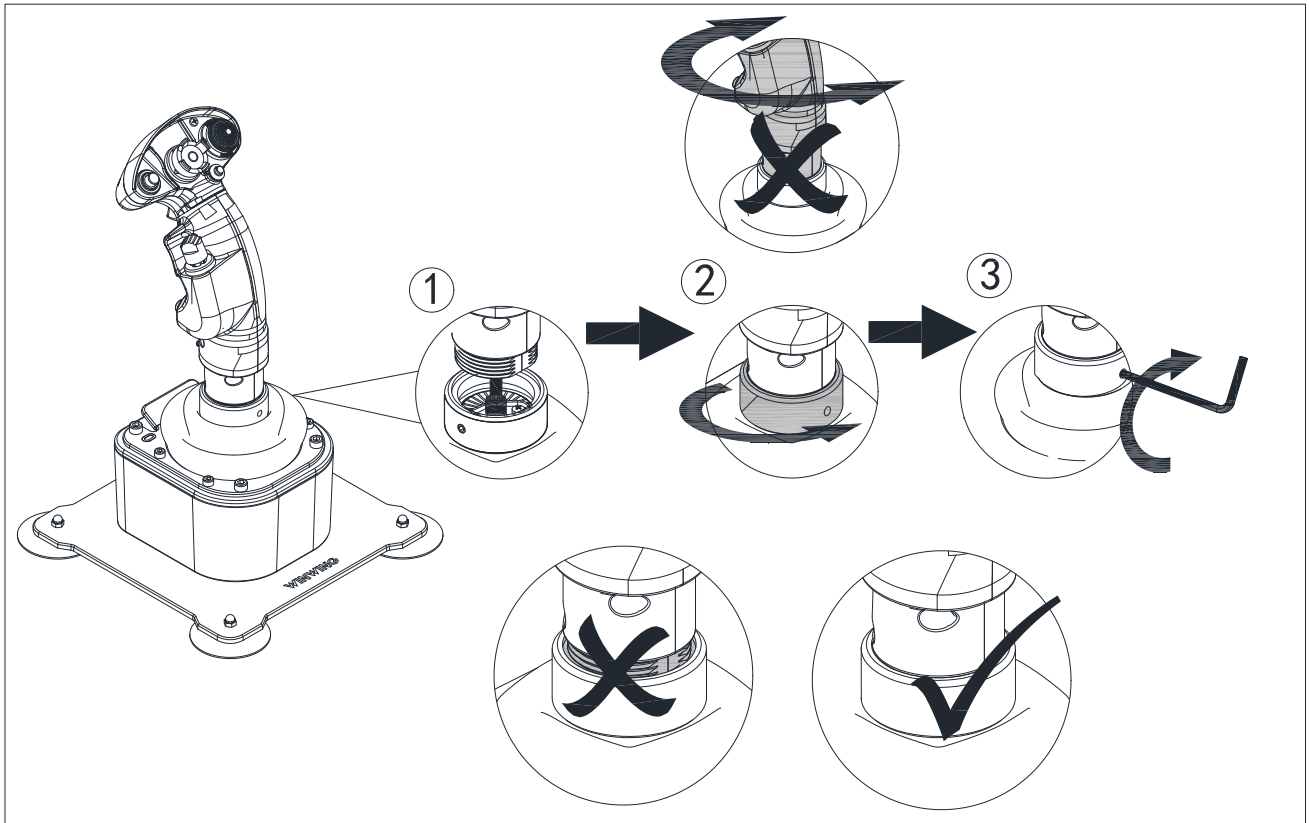
Please refer to *EX1-J2-2 User Manual*.

3.4 Movable multiple force sensor mode

Please refer to *EX2-J2-2 User Manual*.

4 Assembly methods

4.1 Devices connection



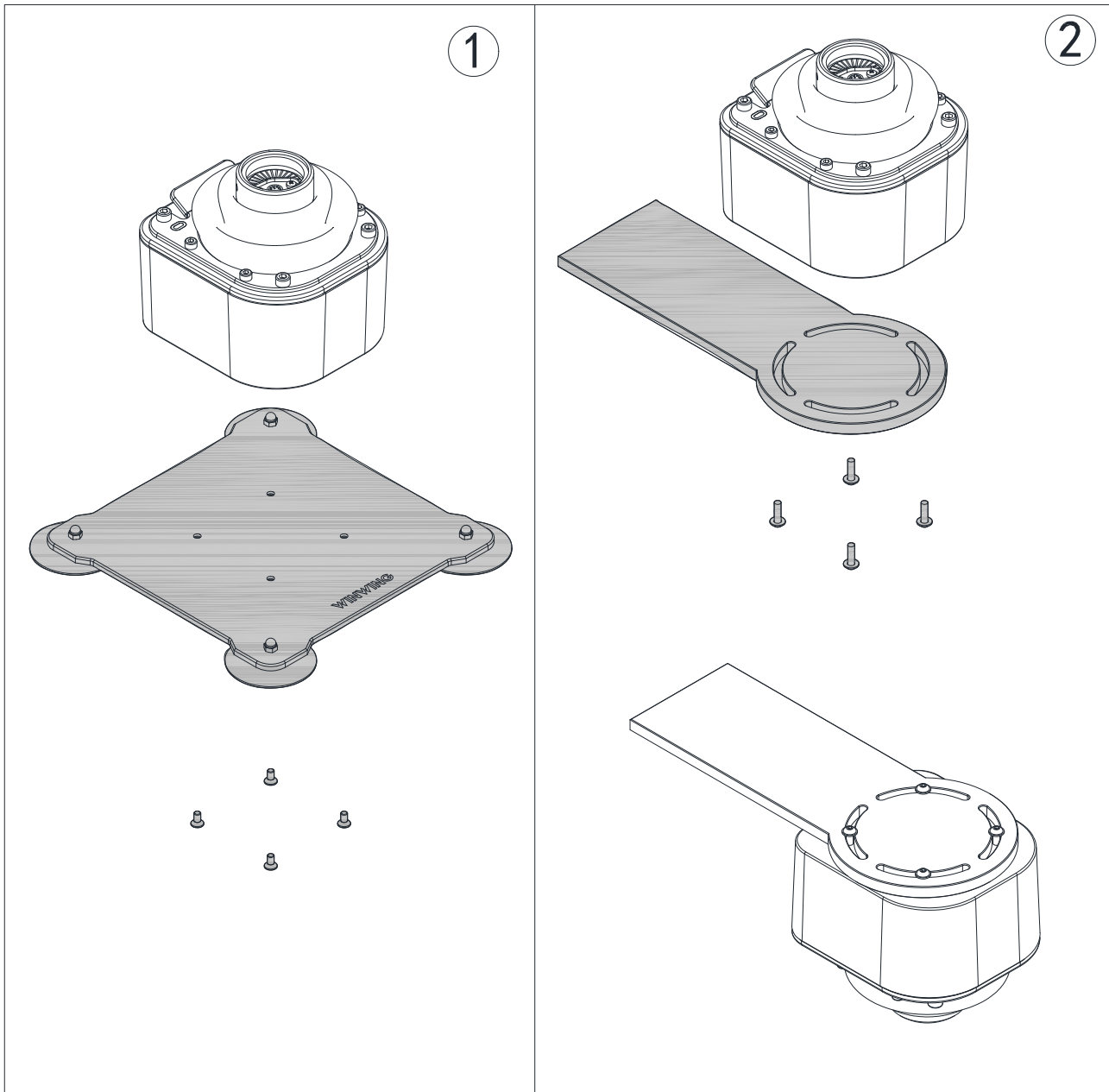
① Align and insert the PS2 connector into the base.

② Twist the knurled cover in the figure counterclockwise, and screw holes should be roughly aligned with the seam of the grip when tightening (Only twist the knurled cover during disassembly, otherwise the cable will be damaged)

③ Use a wrench to tighten jack screw clockwise.

Note: Please reverse the steps above when disassembling.

4.2 Mounting installation



① Remove the 4 screws on the bottom, then remove the plate;

② Put the BASE on the mount, then install screws and spacers (prepared by yourself) from the bottom to fix it on the mounting. .

Note: The mount, screws and spacers should be prepared yourselves. (Additional attention to the length of screws:5 mm M4 screws)

*** This is the final version of the manual, all update will be made online.**

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